TITLE (TIMES NEW ROMAN CAPITAL LETTER 12)

**Author’s Complete Name (Times New Roman Bold 12),**

Institution, country, e-mail (Times New Roman 12)

**(include the above information for each of the authors)**

**Abstract:** 200 words maximum. Times New Roman 12. Line spacing: 1.5.

**Key words:** 4 words maximum.

# 1. Introduction

# Times New Roman 12. Line spacing: 1.5.

# 2. Development

Times New Roman 12. Line spacing: 1.5.

**2.3 Method**

Times New Roman 12. Line spacing: 1.5.

**2.4 Results**

Times New Roman 12. Line spacing:1.5. Tables and figures must be in APA format.

**2.5 Discussion**

Times New Roman 12. Line spacing: 1.5.

**3. Conclusion**

Times New Roman 12. Line spacing: 1.5.

**4. References**

APA format. List alphabetically only those cited. Examples: [1] y [2].

[1] M. A. Gomes, G. L. M. Silveira, and A. A. G. Siqueira. Gait pattern adaptation for an active lower-limb orthosis based on neural networks. Advanced Robotics, 25(1):1903–1925, 2011.

[2] J C Perez Ibarra, W M Santos, H I Krebs, and A A G Siqueira. Adaptive impedance control for robot-aided rehabilitation of ankle movements. In 5th IEEE RAS & EMBS International Conference on Biomedical Robotics and Biomechatronics, pages 664–669, São Paulo, Brazil, 2014.